Introduction

Latent Variable Gaussian Graphical Model (LVGGM):

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 $X_O \in \mathbb{R}^d$ is the observed variables and $X_L \in \mathbb{R}^r$ the latent variables. $\mathbf{X} = (\mathbf{X}_O^{\top}, \mathbf{X}_L^{\top})^{\top} \sim N(\boldsymbol{\mu}, \boldsymbol{\Sigma})$ and sparse precision matrix $\mathbf{\Omega} = \boldsymbol{\Sigma}^{-1}$. Then X_O follows a normal distribution with marginal covariance matrix $\Sigma^* = \Sigma_{OO}$ being the top-left block matrix in Σ . By Schur complement

$$\mathbf{\Omega}^* = (\widetilde{\mathbf{\Sigma}}_{OO})^{-1} = \widetilde{\mathbf{\Omega}}_{OO} - \widetilde{\mathbf{\Omega}}_{OL}\widetilde{\mathbf{\Omega}}_{LL}^{-1}\widetilde{\mathbf{\Omega}}_{LO}.$$

Let $\mathbf{S}^* := \widetilde{\mathbf{\Omega}}_{OO}$ and $\mathbf{L}^* := -\widetilde{\mathbf{\Omega}}_{OL}\widetilde{\mathbf{\Omega}}_{LL}^{-1}\widetilde{\mathbf{\Omega}}_{LO}$. Thus, the precision matrix of LVGGM can be written as

$$\mathbf{\Omega}^* = \mathbf{S}^* + \mathbf{L}^*,$$

where $\|\mathbf{S}^*\|_{0,0} = s^*$ and $rank(\mathbf{L}^*) = r$.



Sparse plus Low-rank Matrix



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Observed

The Proposed Estimator

Suppose that we observe i.i.d. samples X_1, \ldots, X_n from $N(\mathbf{0}, \Sigma^*)$. the negative log-likelihood function

$$p_n(\mathbf{S}, \mathbf{L}) = \operatorname{tr} \left[\widehat{\mathbf{\Sigma}} (\mathbf{S} + \mathbf{L}) \right] - \log |\mathbf{S} + \mathbf{L}|,$$

where $\widehat{\Sigma} = 1/n \sum_{i=1}^{n} X_i X_i^{ op}$ is the sample covariance matrix, and $|\mathbf{S} + \mathbf{L}|$ is the determinant of $\mathbf{\Omega} = \mathbf{S} + \mathbf{L}$.

 \blacktriangleright Due to the symmetry and low-rankness of L, we reparameterize it as $\mathbf{L} = \mathbf{Z}\mathbf{Z}^{\top}$, where $\mathbf{Z} \in \mathbb{R}^{d \times r}$ and r > 0 is the number of latent variables. **Estimator:** we propose a nonconvex estimator using sparsity constrained maximum likelihood:

 $\min_{\mathbf{S},\mathbf{Z}} \quad q_n(\mathbf{S},\mathbf{Z}) = \operatorname{tr}\left[\widehat{\mathbf{\Sigma}}\left(\mathbf{S} + \mathbf{Z}\mathbf{Z}^{\top}\right)\right] - \log|\mathbf{S} + \mathbf{Z}\mathbf{Z}^{\top}|, \quad \text{s.t. } \|\mathbf{S}\|_{0,0} \le s,$

where s > 0 is a tuning parameter that controls the sparsity of S.

The Proposed Algorithm

We present the proposed algorithm here, which consists of two stages: initialization and alternating gradient descent.

Algorithm 1 Alternating Thresholded Gradient Descent (AltGD) for LVGGM

- 1: Input: i.i.d. samples X_1, \ldots, X_n , max number of iterations T, and parameters η, η', r, s . **Stage I: Initialization**
- 2: $\widehat{\boldsymbol{\Sigma}} = \frac{1}{n} \sum_{i=1}^{n} \boldsymbol{X}_{i} \boldsymbol{X}_{i}^{\top}.$
- 3: $\widehat{\mathbf{S}}^{(0)} = \mathcal{HT}_s(\widehat{\mathbf{\Sigma}}^{-1})$, which preserves the *s* largest magnitudes of $\widehat{\mathbf{\Sigma}}^{-1}$.
- 4: Compute SVD: $\widehat{\Sigma}^{-1} \widehat{\mathbf{S}}^{(0)} = \mathbf{U}\mathbf{D}\mathbf{U}^{\top}$, where **D** is a diagonal matrix. Let $\widehat{\mathbf{Z}}^{(0)} = \mathbf{U}\mathbf{D}_r^{1/2}$, where \mathbf{D}_r is the first r columns of **D**.

Stage II: Alternating Gradient Descent

- 5: for $t = 0, \ldots, T 1$ do
- $\widehat{\mathbf{S}}^{(t+0.5)} = \widehat{\mathbf{S}}^{(t)} \eta \nabla_{\mathbf{S}} q_n (\widehat{\mathbf{S}}^{(t)}, \widehat{\mathbf{Z}}^{(t)});$
- $\widehat{\mathbf{S}}^{(t+1)} = \mathcal{HT}_s(\widehat{\mathbf{S}}^{(t+0.5)})$, which preserves the *s* largest magnitudes of $\widehat{\mathbf{S}}^{(t+0.5)}$;
- 8: $\widehat{\mathbf{Z}}^{(t+1)} = \widehat{\mathbf{Z}}^{(t)} \eta' \nabla_{\mathbf{Z}} q_n (\widehat{\mathbf{S}}^{(t)}, \widehat{\mathbf{Z}}^{(t)});$
- 9: **end for** 10: output: $\widehat{\mathbf{S}}^{(T)}, \widehat{\mathbf{Z}}^{(T)}$

Speeding Up Latent Variable Gaussian Graphical Model Estimation via Nonconvex Optimization

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Theoretical Analysis

Assumptions

 \triangleright A1 (Bounded Eigenvalues): $\exists \nu > 0$ such that the eigenvalues of Σ^* are bounded, i.e.,

 $0 < 1/\nu \leq \lambda_{\min}(\Sigma^*) \leq \lambda_{\max}(\Sigma^*) \leq \nu < \infty.$

A2 (Spikiness Condition): the spikiness ratio is defined as $\alpha_{sp}(\mathbf{L}) := d \|\mathbf{L}\|_{\infty,\infty} / \|\mathbf{L}\|_F$. We assume $\exists \alpha^* > 0$ such that

$$\|\mathbf{L}^*\|_{\infty,\infty} = \frac{\alpha_{sp}(\mathbf{L}^*) \cdot \|\mathbf{L}^*\|_F}{d} \le \frac{\alpha^*}{d}.$$

 \triangleright FOS (First-Order Stability): If max{ $||\mathbf{S} - \mathbf{S}^*||_F, d(\mathbf{Z}, \mathbf{Z}^*)$ for some R > 0 and $\mathbf{L} = \mathbf{Z}\mathbf{Z}^{\top}$ and $\mathbf{L}^* = \mathbf{Z}^*\mathbf{Z}^{*\top}$. It holds that

$$\begin{aligned} \left\| \nabla_{\mathbf{S}} p(\mathbf{S}, \mathbf{L}) - \nabla_{\mathbf{S}} p(\mathbf{S}, \mathbf{L}^*) \right\|_F &\leq \gamma_2 \cdot \left\| \mathbf{L} - \mathbf{L}^* \right\|_F, \\ \left\| \nabla_{\mathbf{L}} p(\mathbf{S}, \mathbf{L}) - \nabla_{\mathbf{L}} p(\mathbf{S}^*, \mathbf{L}) \right\|_F &\leq \gamma_1 \cdot \left\| \mathbf{S} - \mathbf{S}^* \right\|_F, \end{aligned}$$

where γ_1, γ_2 are constants and $d(\mathbf{Z}, \mathbf{Z}^*) = \min_{\mathbf{U} \in O(r^*)} \|\mathbf{Z} - \mathbf{U}\|$

► Main Theory

Validation of Initialization: Suppose A1 and A2 hold. Assume $n \ge c\nu^2 r s^* \log d/R^2$ and $s^* \le c' d^2 R^2/(r\alpha^{*2})$, where R is a constant depending on ν . Then with probability at least 1 - C/d, we have

 $\|\widehat{\mathbf{S}}^{(0)} - \mathbf{S}^*\|_F \le R, \quad \text{and} \quad d(\widehat{\mathbf{Z}}^{(0)}, \mathbf{Z}^*) \le R,$

where C > 0 is an absolute constant.

Convergence Rate: Furthermore, suppose **FOS** holds. Let the step sizes $\eta \leq C_0/\nu^2$ and $\eta' \leq C_0/\nu^4$, and the sparsity parameter satisfy $s \geq (4(1/(2\sqrt{\rho})-1)^2+1)s^*$. Let ρ and τ be

$$\rho = \max\left\{1 - \frac{\eta}{\nu^2}, 1 - \frac{\eta'}{\nu^2}\right\}, \qquad \tau = \max\left\{\frac{cs^* \log d}{\nu^4 n}, \frac{crd}{\nu^6 n}\right\}$$

I hen for any $t \ge 1$, with probability at least $1 - C_1/d$, we have

$$\max\left\{\left\|\widehat{\mathbf{S}}^{(t+1)} - \mathbf{S}^*\right\|_F^2, d^2(\widehat{\mathbf{Z}}^{(t+1)}, \mathbf{Z}^*)\right\} \le \frac{\tau}{\underbrace{1 - \sqrt{\rho}}_{\text{statistical error}}} + \underbrace{\sqrt{\rho^{t+1}}_{\text{optimization}}}_{\text{statistical error}}$$

where $C_1 > 0$ is an absolute constant.

Main Remarks

- The initial points returned by the initialization stage of AltGD fall in small neighborhoods of S^* and Z^* if $n = O(s^* \log d)$, which essentially attains the optimal sample complexity for LVGGM estimation. In addition, we require $s^* \leq d^2/(r\alpha^{*2})$, which means the unknown sparse matrix cannot be too dense.
- ▶ The statistical error scales as $\max \{O_p(\sqrt{s^* \log d/n}), O_p(\sqrt{rd/n})\}$, where $O_p(\sqrt{s^* \log d/n})$ corresponds to the statistical error of \mathbf{S}^* , and $O_p(\sqrt{rd/n})$ corresponds to that of \mathbf{L}^* (or equivalently \mathbf{Z}^*). This matches the minimax optimal rate of estimation errors in Frobenius norm for LVGGM estimation.

AltGD enjoys linear convergence rate for optimization error. After $T \geq \max\{O(\log(\nu^4 n/(s^*\log d))), O(\log(\nu^6 n/(rd)))\}$ iterations, the total estimation error achieves the same order as the statistical error.



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merical Simulations

Data Generation: We randomly generated a sparse positive definite matrix $\widetilde{\mathbf{\Omega}} \in \mathbb{R}^{(d+r) imes (d+r)}$, with sparsity $s^* = 0.02d^2$. Set $\mathbf{S}^* := \mathbf{\Omega}_{1:d;1:d}$ and $\mathbf{L}^* := -\widetilde{\mathbf{\Omega}}_{1:d;(d+1):(d+r)} [\widetilde{\mathbf{\Omega}}_{(d+1):(d+r);(d+1):(d+r)}]^{-1} \widetilde{\mathbf{\Omega}}_{(d+1):(d+r);1:d}$. Then we sampled $oldsymbol{X}_1,\ldots,oldsymbol{X}_n\sim N(oldsymbol{0},(oldsymbol{\Omega}^*)^{-1})$, where $oldsymbol{\Omega}^*=oldsymbol{S}^*+oldsymbol{L}^*$. Validation of Convergence Rate:

(a) Estimation error for (b) Estimation error for (c) r fixed and varying (d) s^* fixed and varying n, d and s^* n, d and rFigure: (a)-(b): Evolution of estimation errors with number of iterations t going up with $s^* = 0.02d^2$ and varying d, n and r. (c)-(d): Estimation errors $\|\widehat{f S}^{(T)} - {f S}^*\|_F$ and $\|\widehat{\mathbf{L}}^{(T)} - \mathbf{L}^*\|_F$ versus scaled statistical errors $\sqrt{s^* \log d/n}$ and $\sqrt{rd/n}$.

Comparisons with Convex Methods: AltGD is nearly 50 times faster than the other two methods based on convex algorithms.

Table: Estimation errors in terms of Frobenius norm on different synthetic datasets. Results were reported on 10 replicates in each setting.

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Setting	Method	$\ \widehat{\mathbf{S}}^{(T)} - \mathbf{S}^*\ _F$	$\ \widehat{\mathbf{L}}^{(T)} - \mathbf{L}^*\ _F$	$\ \widehat{\mathbf{\Omega}}^{(T)} - \mathbf{\Omega}^*\ _F$
<i></i>	PPA	$0.7335{\pm}0.0352$	$0.0170 {\pm} 0.0125$	$0.7350{\pm}0.0359$
a = 100, r =	ADMM	$0.7521{\pm}0.0288$	$0.0224{\pm}0.0115$	$0.7563{\pm}0.0298$
2, n = 2000	AltGD	$0.6241{\pm}0.0668$	$0.0113{\pm}0.0014$	$0.6236 {\pm} 0.0669$
1 500	PPA	0.9803±0.0192	0.0195±0.0046	0.9813±0.0192
a = 500, r =	ADMM	$1.0571{\pm}0.0135$	$0.0294{\pm}0.0041$	$1.0610{\pm}0.0134$
5, n = 10000	AltGD	$0.8212{\pm}0.0143$	$0.0125{\pm}0.0000$	0.8210±0.0143
1 1000	PPA	$1.1620{\pm}0.0177$	0.0224±0.0034	$1.1639{\pm}0.0179$
d = 1000, r =	ADMM	$1.1867{\pm}0.0253$	$0.0356{\pm}0.0033$	$1.1869{\pm}0.0254$
$8, n = 2.5 \times 10^{11}$	AltGD	$0.9016 {\pm} 0.0245$	$0.0167{\pm}0.0030$	$0.9021{\pm}0.0244$
1 5000	PPA	1.4822 ± 0.0302	0.0371±0.0052	$1.4824{\pm}0.0120$
d = 5000, r = $10, n = 2 \times 10^5$	ADMM	$1.5010{\pm}0.0240$	$0.0442{\pm}0.0068$	$1.5012{\pm}0.0240$
	AltGD	1.3449 ± 0.0073	0.0208 ± 0.0014	$1.3449 {\pm} 0.0084$

Experiments on Genomic Datasets

Experiments on TCGA breast cancer gene expression data (n = 601 samples and d = 299)TFs) to infer the regulatory

Table: Summary of CPU time on luminal subtype breast cancer dataset. Method GLasso PPA ADMM AltGD Time (s) 38.63 85.01 7.67 0.15

network. Methods based on LVGGMs are able to recover more edges accurately than graphical Lasso because of the intervention of latent variables. AltGD runs much faster than the convex methods.

the ones inferred by the respective methods; green edges are incorrectly inferred interactions.

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